

# Pseudo-Exhaustive Testing, Part I

Joseph Morgan, Principal Research Statistician



# Testing Complex Engineered Systems

## What is Testing?

*“Testing is the process of executing a ... system with the intent of finding errors.<sup>1</sup>”*

<sup>1</sup>G. Myers, *The Art of Software Testing*, Wiley, 1979

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# Testing Complex Engineered Systems

**Where are the bugs?**

*“Bugs lurk in corners and congregate at boundaries.<sup>1</sup>”*

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# Testing Complex Engineered Systems

Where are the **faults**?

*“**Faults** lurk in corners and congregate at boundaries.<sup>1</sup>”*

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# Testing Complex Engineered Systems

## The Testing Challenge

Given a complex engineered system and a testing budget:

1. **Selection problem:** How do you select test cases from the input space of the system so that the chance of finding faults, while staying within budget, is maximized?
2. **Quality problem:** Can you make informed assertions about “*fitness for use*” as testing unfolds?
3. **Oracle problem:** How do you determine expected behavior for each test case?

# Testing Complex Engineered Systems

## Combinatorial Testing

A family of test case selection strategies used to test complex engineered systems.

For a complex engineered system, with  $m$  inputs, such as a software system, a strength  $t$  covering array will ensure that all possible combinations of the values for any set of  $t \leq m$  inputs will appear in the derived test suite at least once.

# Testing Complex Engineered Systems

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## Combinatorial Testing

Partly addresses the testing challenge.

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2. **Quality problem:** Can you make informed assertions about “*fitness for use*” as testing unfolds?
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# Testing Complex Engineered Systems

Alessandro Orso & Gregg Rothermel<sup>1</sup>



Two questions

1. What do you think are the most significant contributions to testing since 2000?
2. What do you think are the biggest open challenges and opportunities in this area?

<sup>1</sup>Orso, Alessandro, and Gregg Rothermel. "Software testing: a research travelogue (2000–2014)." *Future of Software Engineering Proceedings*. 2014. 117-132.





# Covering Arrays

An introduction

# Covering arrays - Preliminaries

## Definition

A covering array  $\mathbf{CA}_\lambda(N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_m))$  is an  $N \times m$  array such that the  $i$ -th column contains  $v_i$  distinct symbols. If the array has the property that, for any  $t$  column projection ( $t \geq 1$ ), all  $\prod_{k=1}^t v_{f(k)}$  combinations of symbols exist at least  $\lambda$  times ( $f(k)$  the  $k^{\text{th}}$  column of the projection), then it is a  $t$ -covering array.

*Note:* Exponential notation is usually used for the symbol specification (i.e.  $(3 \cdot 2^3)$  instead of  $(3 \cdot 2 \cdot 2 \cdot 2)$ ).

# Covering arrays - Preliminaries

## Definition

The size of a covering array is referred to as the covering array number  $\mathbf{CAN}_\lambda(t, (v_1 \cdot v_2 \cdot \dots \cdot v_m))$ ,

$$\mathbf{CAN}_\lambda(t, (v_1 \cdot v_2 \cdot \dots \cdot v_m)) = \min\{N: \exists \mathbf{CA}_\lambda(N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_m))\}.$$

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<b>N</b>	4	5	6	7	8	9	10	11	12	13	14
<b>m</b>	3	4	10	15	35	56	126	210	462	792	1716

$$\mathbf{CA}(N; 2, 2^m), m \leq 1716$$

# Covering arrays - Preliminaries

## Notes:

1. Consider the covering array  $\mathbf{CA}_\lambda(N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_m))$ . If for any  $t$  column projection all combinations of symbols exist **exactly  $\lambda$  times** then it is a  $t$ -covering **orthogonal** array of index  $\lambda$ .

**Takeaway:** Orthogonal arrays are a special type of covering array.

2. A  $t$ -covering array is optimal if  $N$  is minimal for fixed  $t$ ,  $m$ , and  $(v_1 \cdot v_2 \cdot \dots \cdot v_m)$ .
3. When  $\lambda=1$  (the most common case) we usually drop the subscript.

# Covering arrays - Preliminaries


1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

**CA(6; 2, 2<sup>5</sup>)**

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

**CA(12; 3, 2<sup>5</sup>)**

# Covering arrays - Preliminaries



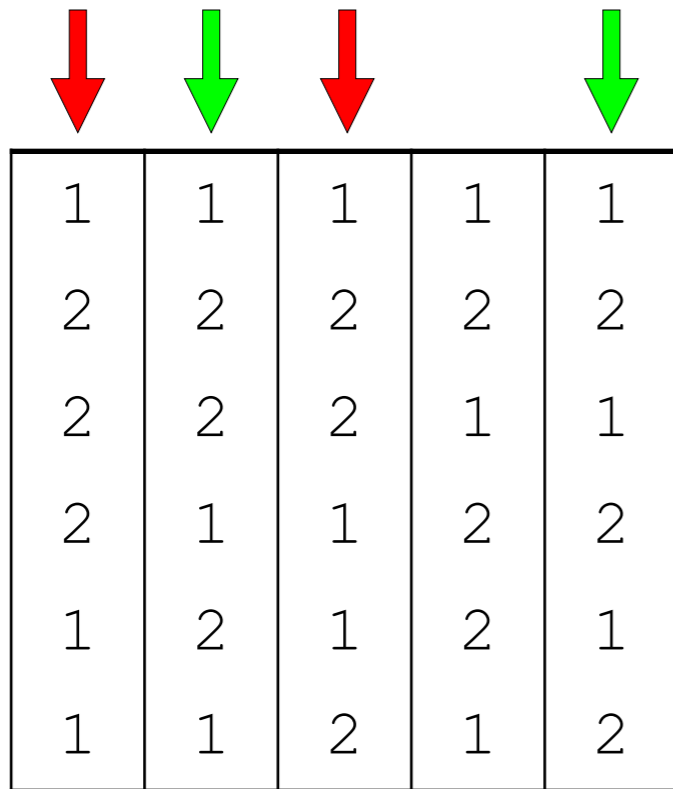
1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

**CA(6; 2, 2<sup>5</sup>)**

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

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# Covering arrays - Preliminaries




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1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

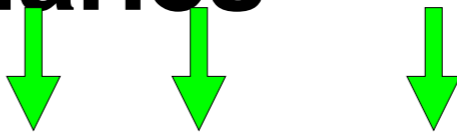
**CA(12; 3, 2<sup>5</sup>)**

# Covering arrays - Preliminaries



1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

**CA(6; 2, 2<sup>5</sup>)**



1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
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1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

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1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

Optimal<sup>1</sup>

**CA(6; 2, 2<sup>5</sup>)**

Not optimal<sup>2</sup>  
CAN = 10

**CA(12; 3, 2<sup>5</sup>)**

1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

<sup>1</sup> A. Renyi, 1948


<sup>2</sup> K. Johnson & R. Entringer, 1989

# Covering arrays - Preliminaries

1	1	2	1	2	2	2	1	1	1
1	2	1	2	1	1	2	2	2	1
1	3	1	1	2	1	1	1	2	2
2	1	1	2	1	2	1	2	2	2
2	2	2	2	2	1	1	1	1	2
2	3	2	1	2	1	2	1	1	1
3	1	1	1	2	1	1	2	1	1
3	2	1	1	1	2	1	1	1	1
3	3	2	2	1	2	2	2	2	2

**CA(9; 2, (3<sup>2</sup>·2<sup>8</sup>))**


# Covering arrays - Preliminaries



1	1	2	1	2	2	2	1	1	1
1	2	1	2	1	1	2	2	2	1
1	3	1	1	2	1	1	1	2	2
2	1	1	2	1	2	1	2	2	2
2	2	2	2	2	1	1	1	1	2
2	3	2	1	2	1	2	1	1	1
3	1	1	1	2	1	1	2	1	1
3	2	1	1	1	2	1	1	1	1
3	3	2	2	1	2	2	2	2	2

**CA(9; 2, (3<sup>2</sup>·2<sup>8</sup>))**

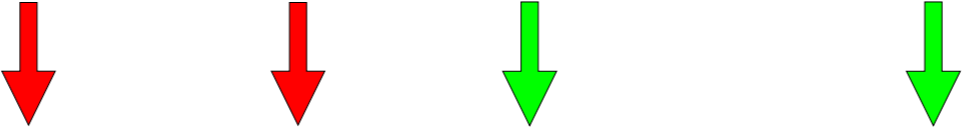
# Covering arrays - Preliminaries



1	1	2	1	2	2	2	1	1	1
1	2	1	2	1	1	2	2	2	1
1	3	1	1	2	1	1	1	2	2
2	1	1	2	1	2	1	2	2	2
2	2	2	2	2	1	1	1	1	2
2	3	2	1	2	1	2	1	1	1
3	1	1	1	2	1	1	2	1	1
3	2	1	1	1	2	1	1	1	1
3	3	2	2	1	2	2	2	2	2

**CA(9; 2, (3<sup>2</sup>·2<sup>8</sup>))**

# Covering arrays - Preliminaries

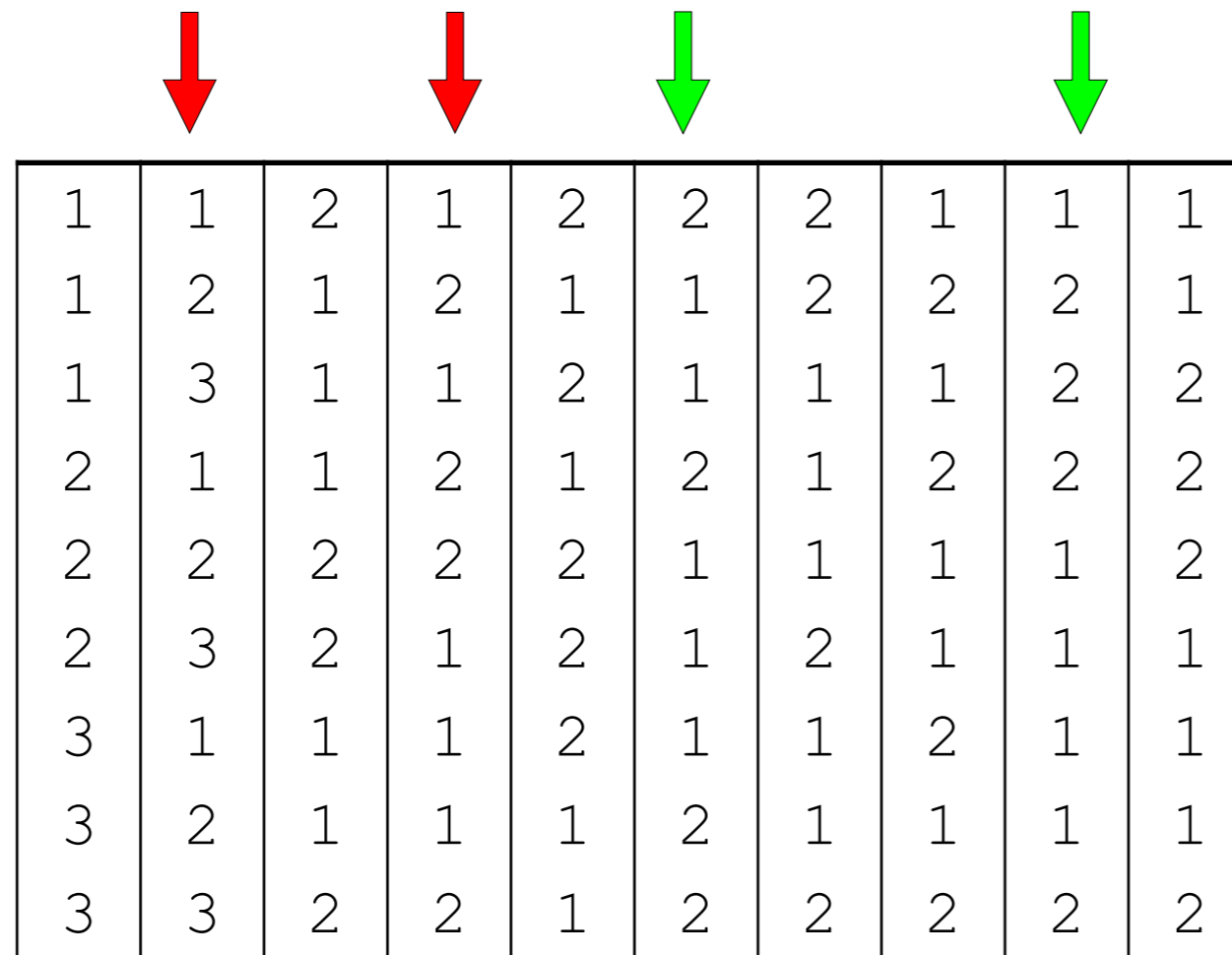


1	1	2	1	2	2	2	1	1	1
1	2	1	2	1	1	2	2	2	1
1	3	1	1	2	1	1	1	2	2
2	1	1	2	1	2	1	2	2	2
2	2	2	2	2	1	1	1	1	2
2	3	2	1	2	1	2	1	1	1
3	1	1	1	2	1	1	2	1	1
3	2	1	1	1	2	1	1	1	1
3	3	2	2	1	2	2	2	2	2

**CA(9; 2, (3<sup>2</sup> · 2<sup>8</sup>))**

Optimal

# Covering arrays - Preliminaries



1	1	2	1	2	2	2	1	1	1
1	2	1	2	1	1	2	2	2	1
1	3	1	1	2	1	1	1	2	2
2	1	1	2	1	2	1	2	2	2
2	2	2	2	2	1	1	1	1	2
2	3	2	1	2	1	2	1	1	1
3	1	1	1	2	1	1	2	1	1
3	2	1	1	1	2	1	1	1	1
3	3	2	2	1	2	2	2	2	2

**CA**(9; 2, ( $3^2 \cdot 2^8$ ))

Optimal

*Note:* Using a search algorithm, we know that **CAN**(2, ( $3^2 \cdot 2^{20}$ )) = 9.

# Covering arrays - Preliminaries

## Definition<sup>1</sup>

Consider the covering array  $\mathbf{CA}_\lambda(N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_m))$ . Let  $n_i$  be the number of distinct  $t$  tuples for the  $i^{\text{th}}$  projection,  $p_i$  the number of possible  $t$  tuples *for the*  $i^{\text{th}}$  projection,  $r$  the number of rows, and  $M = {}_K C_t$  the number of  $t$  column projections that can be obtained from  $K$  columns.

*Note:*  $p_i = \prod_{k=1}^t v_{f(k)}$  where  $f(k)$  is the  $k^{\text{th}}$  column of the  $i^{\text{th}}$  projection.

<sup>1</sup>S. Dalal & C. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

# Covering arrays - Preliminaries

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$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i.$$

*Note:*  $p_i = \prod_{k=1}^t v_{f(k)}$  where  $f(k)$  is the  $k^{\text{th}}$  column of the  $i^{\text{th}}$  projection.

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# Covering arrays - Preliminaries

## Definition<sup>1</sup>

In simple terms, *t*-Coverage is the ratio of the number of distinct *t* tuples, to the number of possible *t* tuples, averaged over all *t* column projections ( $1 \leq t \leq K$ ).

*Note:* For a comprehensive treatment of covering array metrics see:

Kuhn, D. R., et al. "Combinatorial coverage measurement concepts and applications." *2013 IEEE 6th International Conference on Software Testing, Verification and Validation Workshops*. IEEE, 2013.

<sup>1</sup>S. Dalal & C. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

# Covering arrays - Preliminaries

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1	1	1	1	1
2	2	2	2	2
2	2	2	1	1
2	1	1	2	2
1	2	1	2	1
1	1	2	1	2

**CA(6; 2, 5, 2)**

# Covering arrays - Preliminaries

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1	1	1	1	1
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**CA(6; 2, 5, 2)**

<i>t</i>	Coverage
2	100.0
3	70.0
4	37.5

# Covering arrays - Preliminaries

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1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
1	2	2	2	1

**CA(12; 3, 5, 2)**

# Covering arrays - Preliminaries

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1	1	1	1	1
1	1	2	1	1
1	2	1	1	2
1	2	2	1	2
2	1	1	2	1
2	1	2	2	1
2	2	1	2	2
2	2	2	2	2
1	1	1	2	2
2	2	1	1	1
2	1	2	1	2
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# Testing Complex Engineered Systems

**Question:** How do we get to combinatorial testing from covering arrays?

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**Answer:** It is a mapping exercise!

# Testing Complex Engineered Systems

Consider a system to be tested (i.e. SUT), such as a function with  $m$  arguments/inputs, a GUI with  $m$  controls/inputs, a configuration with  $m$  options/inputs (e.g. software system preferences, ML hyper-parameters, compiler options).

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**Covering Array**

Columns

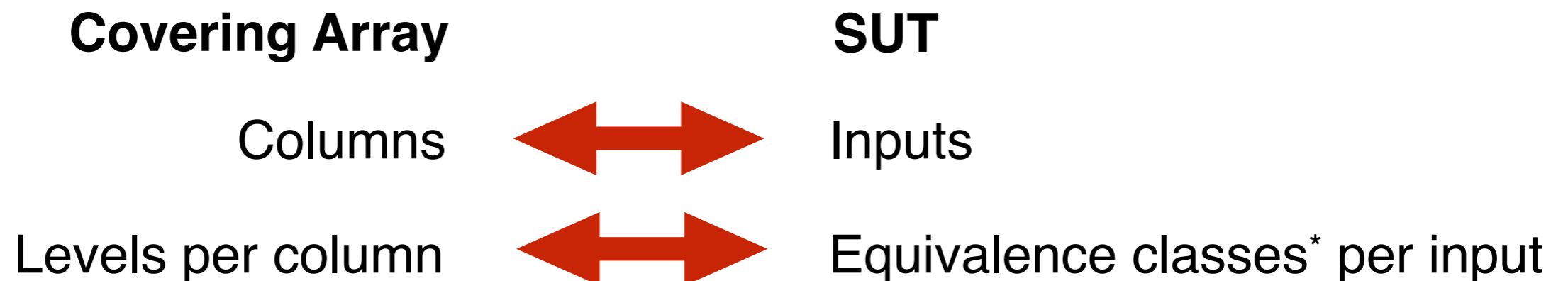


**SUT**

Inputs

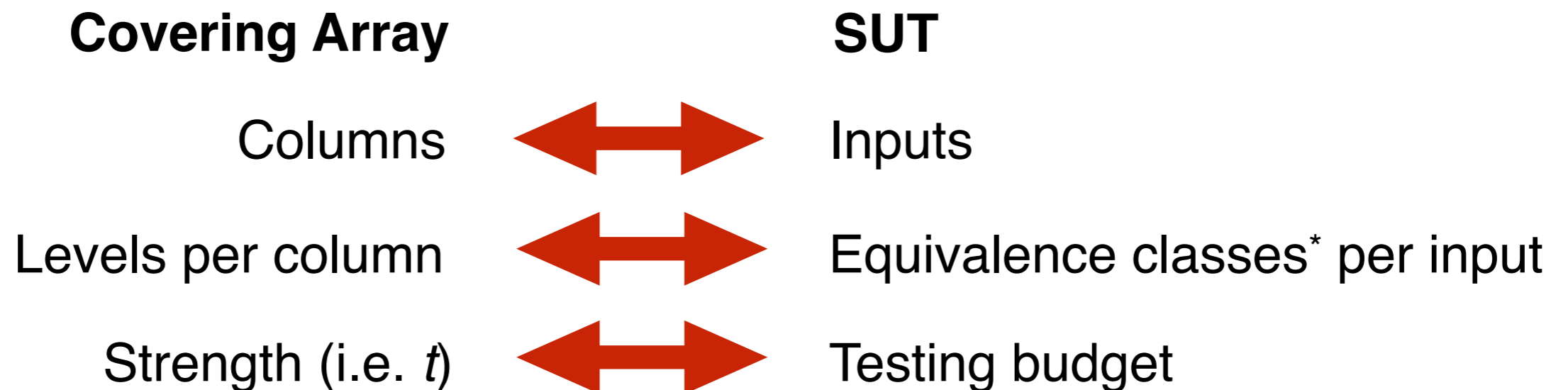
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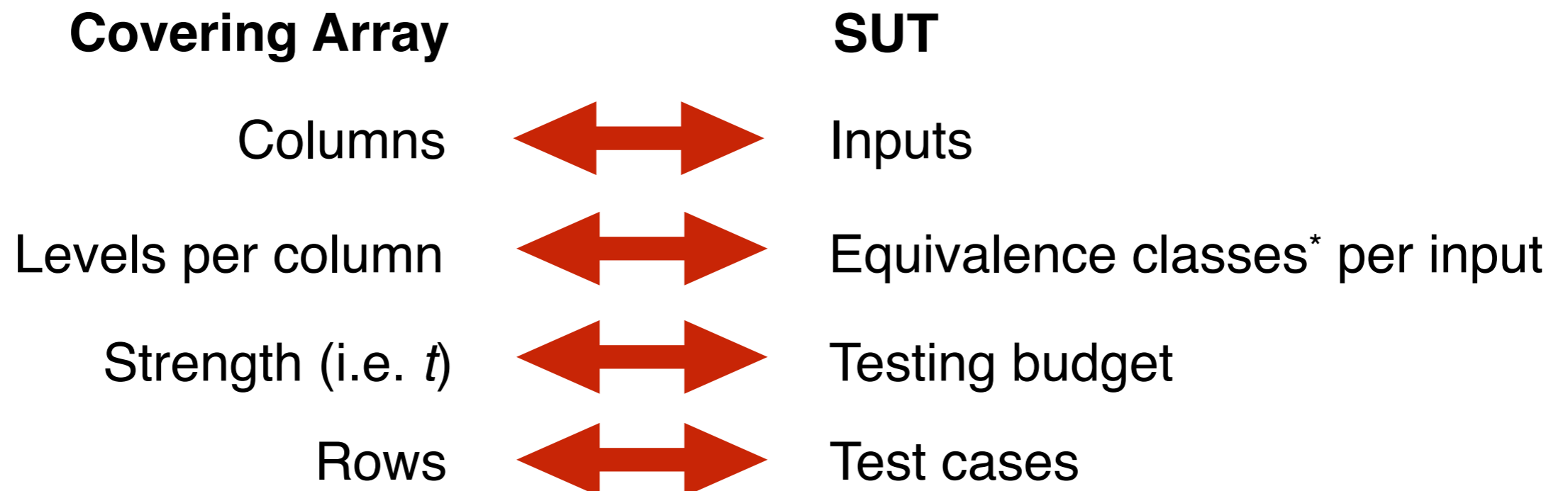
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# Illustrative Example

Air to ground missile system

# Combinatorial Testing: Air to ground missile system

Consider a software system controlling the state of an air to ground missile system (Dalal & Mallows<sup>1</sup>).

	Input	Type
1	Altitude	<i>continuous</i>
2	Attack angle	<i>continuous</i>
3	Bank angle	<i>continuous</i>
4	Speed	<i>continuous</i>
5	Pitch	<i>continuous</i>
6	Roll	<i>continuous</i>
7	Yaw	<i>continuous</i>
8	Ambient Temperature	<i>continuous</i>
9	Pressure	<i>continuous</i>
10	Wind Velocity	<i>continuous</i>

<sup>1</sup>S. R. Dalal & C. L. Mallows, "Factor-covering designs for testing software," *Technometrics*, 40(3), 1998, 234-243.

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9	Pressure	<i>continuous</i>
10	Wind Velocity	<i>continuous</i>

## Challenge:

We are interested in deriving test cases to effectively validate “...response during attack maneuvering.”

<sup>1</sup>S. R. Dalal & C. L. Mallows, “Factor-covering designs for testing software,” *Technometrics*, 40(3), 1998, 234-243.

# Combinatorial Testing - Air to ground missile system

Remember that inputs correspond to columns. Let us say that there are two equivalence classes per input (i.e. two levels per column), then the design specification is:

	Column	Levels
1	Altitude	<i>low, high</i>
2	Attack angle	<i>low, high</i>
3	Bank angle	<i>low, high</i>
4	Speed	<i>low, high</i>
5	Pitch	<i>low, high</i>
6	Roll	<i>low, high</i>
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8	Ambient Temperature	<i>low, high</i>
9	Pressure	<i>low, high</i>
10	Wind Velocity	<i>low, high</i>

*Note:* With two levels per column, the input space is  $2^{10} = 1024$  points!

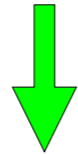
# Combinatorial Testing - Air to ground missile system

“Naive” approach:

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	high	low	high	high	high	low
high	high	high	high	low	high	low	low	low	high

# Combinatorial Testing - Air to ground missile system

“Naive” approach:



Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	high	low	high	high	high	low
high	high	high	high	low	high	low	low	low	high

# Combinatorial Testing - Air to ground missile system

“Naive” approach:



Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	high	low	high	high	high	low
high	high	high	high	low	high	low	low	low	high

high  
low

low  
high

Missing level combinations!

# Combinatorial Testing - Air to ground missile system

“Naive” approach:



Otherwise known as an  
“All values testing” strategy.

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	high	low	high	high	high	low
high	high	high	high	low	high	low	low	low	high

high  
low

low  
high

Missing level combinations!

# Combinatorial Testing - Air to ground missile system

Covering array approach:

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	low	low	low	low	low	low
low	low	low	low	high	high	high	high	high	high
low	high	high	high	low	low	low	high	high	high
high	low	high	high	low	high	high	low	low	high
high	high	low	high	high	low	high	low	high	low
high	high	high	low	high	high	low	high	low	low

**CA(6; 2, 10, 2)**

# Combinatorial Testing - Air to ground missile system

Covering array approach:



Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	low	low	low	low	low	low
low	low	low	low	high	high	high	high	high	high
low	high	high	high	low	low	low	high	high	high
high	low	high	high	low	high	high	low	low	high
high	high	low	high	high	low	high	low	high	low
high	high	high	low	high	high	low	high	low	low

**CA(6; 2, 10, 2)**

# Combinatorial Testing - Air to ground missile system

Covering array approach:



Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	low	low	low	low	low	low
low	low	low	low	high	high	high	high	high	high
low	high	high	high	low	low	low	high	high	high
high	low	high	high	low	high	high	low	low	high
high	high	low	high	high	low	high	low	high	low
high	high	high	low	high	high	low	high	low	low

**CA(6; 2, 10, 2)**

Optimal<sup>1</sup>

<sup>1</sup> A. Renyi, 1948

# Combinatorial Testing - Air to ground missile system

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

Air to ground missile system, **CA(6; 2, 10, 2)**:

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	low	low	low	low	low	low
low	low	low	low	high	high	high	high	high	high
low	high	high	high	low	low	low	high	high	high
high	low	high	high	low	high	high	low	low	high
high	high	low	high	high	low	high	low	high	low
high	high	high	low	high	high	low	high	low	low

# Combinatorial Testing - Air to ground missile system

$$t\text{-Coverage} = \frac{1}{M} \sum_{i=1}^M n_i / p_i$$

Air to ground missile system, **CA**(6; 2, 10, 2):

<i>t</i>	Coverage
2	100.0
3	68.8
4	37.1

Altitude	Attack Angle	Bank Angle	Speed	Pitch	Roll	Yaw	Ambient Temp	Pressure	Wind Velocity
low	low	low	low	low	low	low	low	low	low
low	low	low	low	high	high	high	high	high	high
low	high	high	high	low	low	low	high	high	high
high	low	high	high	low	high	high	low	low	high
high	high	low	high	high	low	high	low	high	low
high	high	high	low	high	high	low	high	low	low

# Testing Complex Engineered Systems

## Combinatorial Testing: Empirical evidence

**Question:** Is combinatorial testing an effective way to test complex engineered systems?

# Testing Complex Engineered Systems

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**Answer:** Yes! Kuhn et al.<sup>1</sup> examined several classes of software systems and discovered the following.

	% faults detected			
	t=2	t=3	t=4	t=5
Medical device software	95	99	100	100
Browser application	70	90	95	96
Server software	75	95	96	99
Network security	62	89	99	100
TCAS - Avionics System	54	74	89	100

<sup>1</sup>D. Kuhn & D. Wallace, & A. Gallo, "Software fault interactions and implications for software testing," IEEE Trans. SE, v30(6) (2004), 418-421.

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Very high availability & reliability requirements!

<sup>1</sup>D. Kuhn & D. Wallace, & A. Gallo, "Software fault interactions and implications for software testing," IEEE Trans. SE, v30(6) (2004), 418-421.

# Covering arrays

## ***Note:***

In practice, systems and software validation problems come with constraints. Consider a GUI that contains a variety of controls, such as checkboxes, combo boxes, etc., where some setting of a particular control precludes settings of some other control. In discussing testing configurable systems, Myra Cohen<sup>1</sup> states:

*“Constraints may arise due to any number of reasons, for example, inconsistencies between certain hardware components, limitations due to available memory and software size, or simply marketing decisions.”*

Constraints are referred to as *disallowed combinations* or *forbidden interactions*.

<sup>1</sup>M. Cohen, M. Dwyer, J. Shi, “Interaction testing of highly-configurable systems in the presence of constraints,” IEEE TSE, 2008, 633-650.

# Covering arrays

CA's are not sufficient, we need an extension!

# Constrained covering arrays

## Definition<sup>1</sup>

A *constrained covering array* **CCA**( $N; t, (v_1 \cdot v_2 \cdot \dots \cdot v_k), \phi$ ) is an  $N \times k$  array such that the  $i$ -th column contains  $v_i$  distinct symbols and  $\phi$  is a set of  $p$ -tuples ( $2 \leq p \leq k$ ) such that each tuple is a set of two or more column/value pairs identifying a disallowed combination. If for any  $t$  coordinate projection, all **possible** combinations of symbols exist, then it is a  **$t$ -covering array** and is optimal if  $N$  is minimal for fixed  $t$ ,  $k$ ,  $(v_1 \cdot v_2 \cdot \dots \cdot v_k)$ , and  $\phi$ .

*Note:* Let us say that the symbol set for columns  $c_1$  and  $c_2$  is  $\{1, 2\}$  and the symbol combination  $(2, 1)$  is not allowed then  $\phi = \{(c_1, 2), (c_2, 2)\}$ .

<sup>1</sup>J. Morgan, "Combinatorial Testing: An approach to systems and software testing based on covering arrays," in *Analytic Methods in Systems and Software Testing*, eds., F. Ruggeri, R. Kennett, & F. Faltin, Wiley, 2018.

# Constrained covering arrays

Consider a **CCA**(9; 2,  $(3^2 \cdot 2^3)$ ,  $\phi$ ) where  $\phi = \{(c_1, 1), (c_3, 1)\}$ .

It is usually convenient to express  $\phi$  more compactly. Cohen<sup>1</sup>, suggests a shorthand exponent notation,  $p^k$ , to indicate  $k$   $p$ -tuples. In this case,  $\phi = \{2^1\}$ .

$c_1$	$c_2$	$c_3$	$c_4$	$c_5$
1	1	2	2	1
1	2	2	1	2
1	3	2	2	2
2	1	1	2	2
2	2	2	2	2
2	3	2	1	1
3	1	2	1	1
3	2	1	2	1
3	3	1	1	2

**CCA**(9; 2,  $(3^2 \cdot 2^3)$ ,  $\phi = \{2^1\}$ )

<sup>1</sup>M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

# Constrained covering arrays

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$c_1$	$c_2$	$c_3$	$c_4$	$c_5$
1	1	2	2	1
1	2	2	1	2
1	3	2	2	2
2	1	1	2	2
2	2	2	2	2
2	3	2	1	1
3	1	2	1	1
3	2	1	2	1
3	3	1	1	2

**CCA**(9; 2,  $(3^2 \cdot 2^3)$ ,  $\phi = \{2^1\}$ )

Optimal

Exponent notation

<sup>1</sup>M. Cohen, M. Dwyer, J. Shi, "Interaction testing of highly-configurable systems in the presence of constraints," IEEE TSE, 2008, 633-650.

# Testing Complex Engineered Systems

## Combinatorial Testing

If  $t \ll m$  then the cost savings is dramatic when compared to exhaustive testing.

# Testing Complex Engineered Systems

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If  $t \ll m$  then the cost savings is dramatic when compared to exhaustive testing.

Consider the **CAN** for strength 2 binary covering arrays:

<b>N</b>	4	5	6	7	8	9	10	11	12	13	14
<b>m</b>	3	4	10	15	35	56	126	210	462	792	1716

$$\mathbf{CA}(N; 2, 2^m), m \leq 1716$$

# Testing Complex Engineered Systems

## Takeaways

1. Given a system with  $m$  inputs, a strength  $t$  covering array may be used to generate a test suite in which all  $t$ -way interactions are covered by at least one test case. If  $t \ll m$  then the cost savings is dramatic when compared to exhaustive testing.
2. Covering arrays are an effective and efficient tool for deriving test suites to validate complex engineered systems such as software systems.

# Testing Complex Engineered Systems

## Takeaways

1. Given a system with  $m$  inputs, a strength  $t$  covering array may be used to generate a test suite in which all  $t$ -way interactions are covered by at least one test case. If  $t \ll m$  then the cost savings is dramatic when compared to exhaustive testing.
2. Covering arrays are an effective and efficient tool for deriving test suites to validate complex engineered systems such as software systems.

## *Pseudo-exhaustive testing*<sup>1</sup>

<sup>1</sup>D. Kuhn & V. Okum, "Pseudo-exhaustive testing for software," Proc. 30<sup>th</sup> IEEE/NASA Software Engineering Workshop, (2006).

# Testing Complex Engineered Systems

## Historical Aside: Combinatorial Testing milestones

1. **Orthogonal latin squares:** In 1985, Mandl proposed orthogonal latin squares as the basis of a test case selection strategy for validating the Ada compiler.
2. **Orthogonal arrays:** In 1987, Tatsumi et al. proposed orthogonal arrays as the basis of a test case selection strategy.
3. **Covering arrays:** In 1996, Cohen et al. proposed covering arrays as the basis of a test case selection strategy.

# Case Study #1

## Traffic Collision Avoidance System

# Traffic Collision Avoidance System (TCAS)

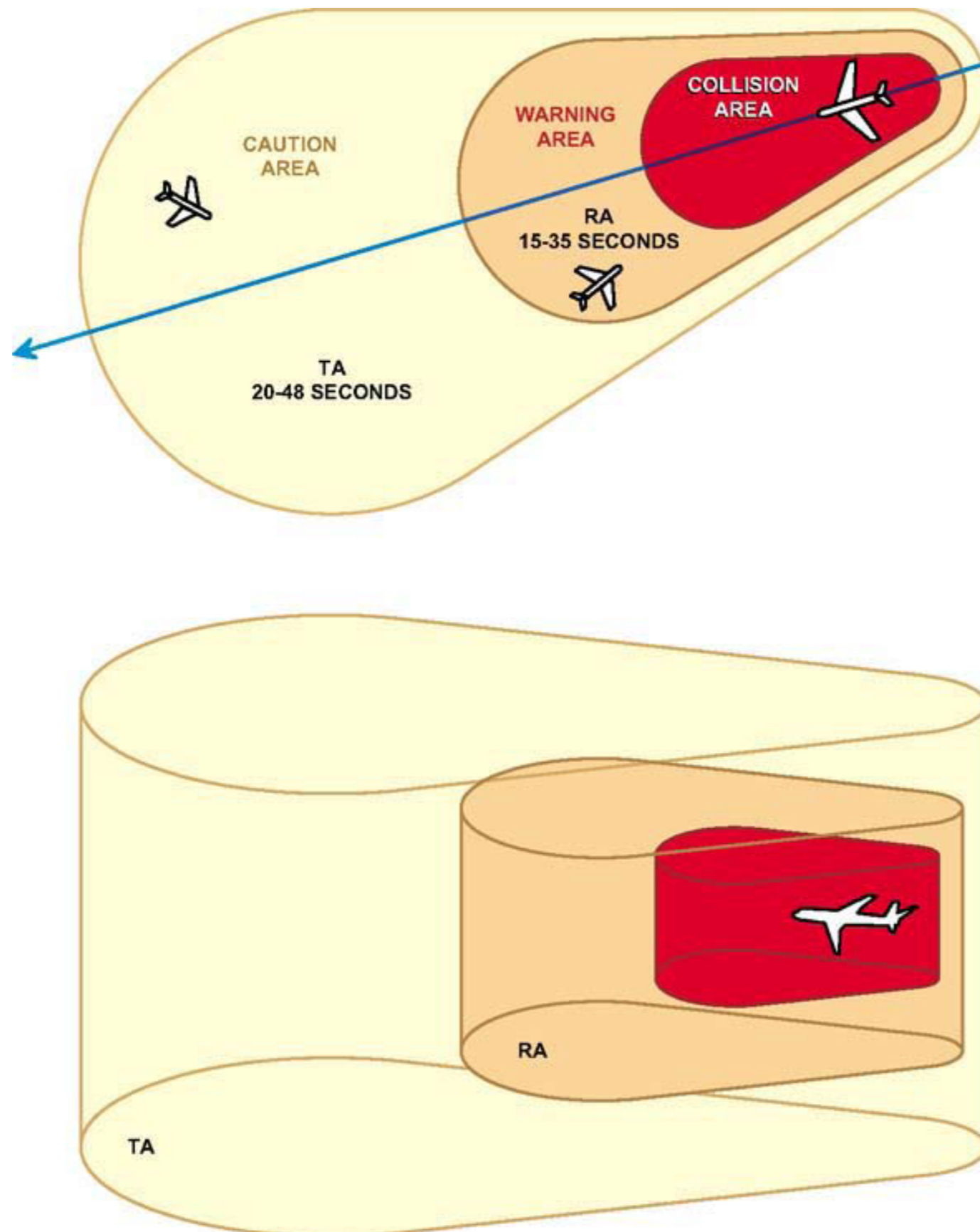


Fig 1. Protection Envelope

# TCAS

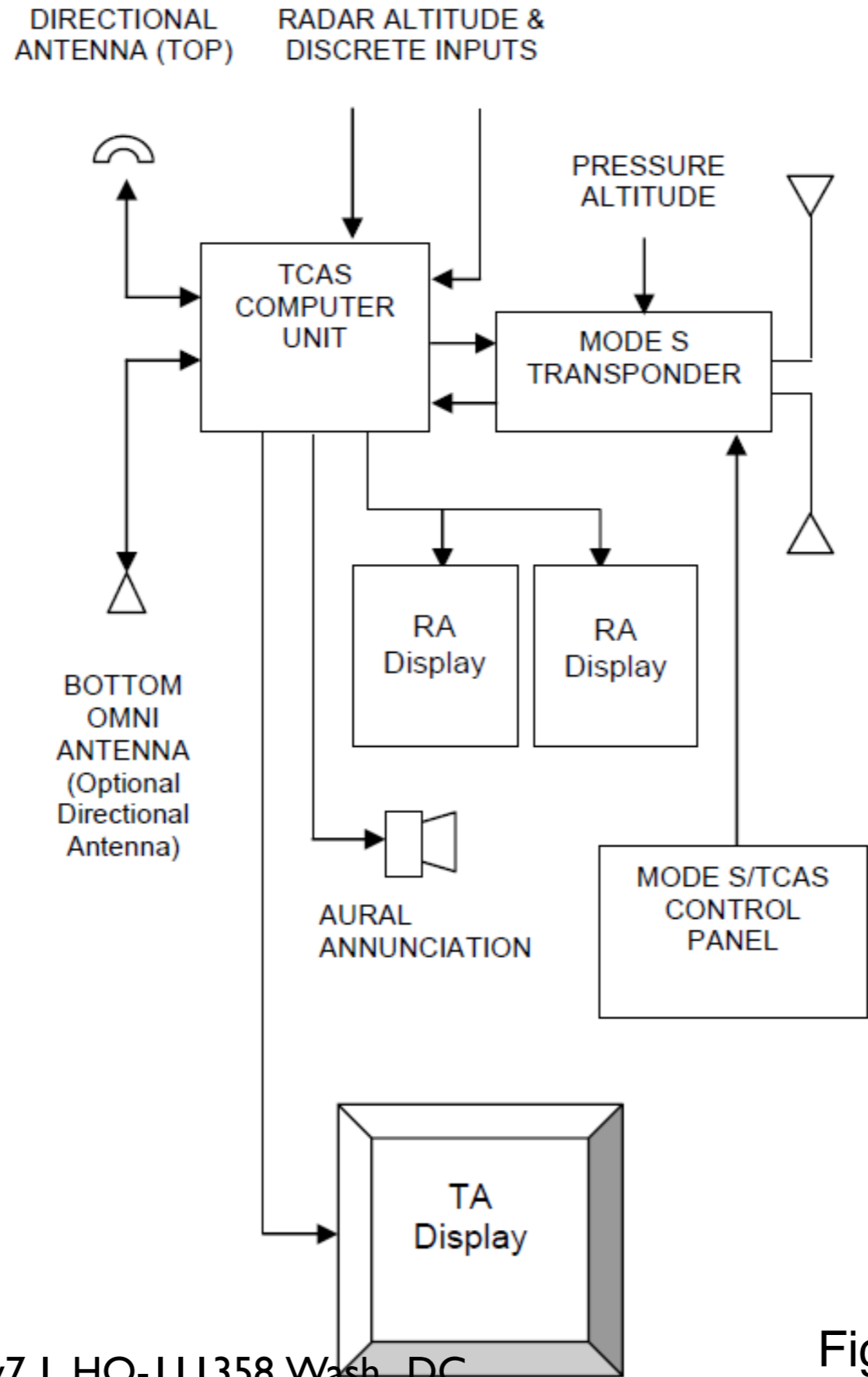
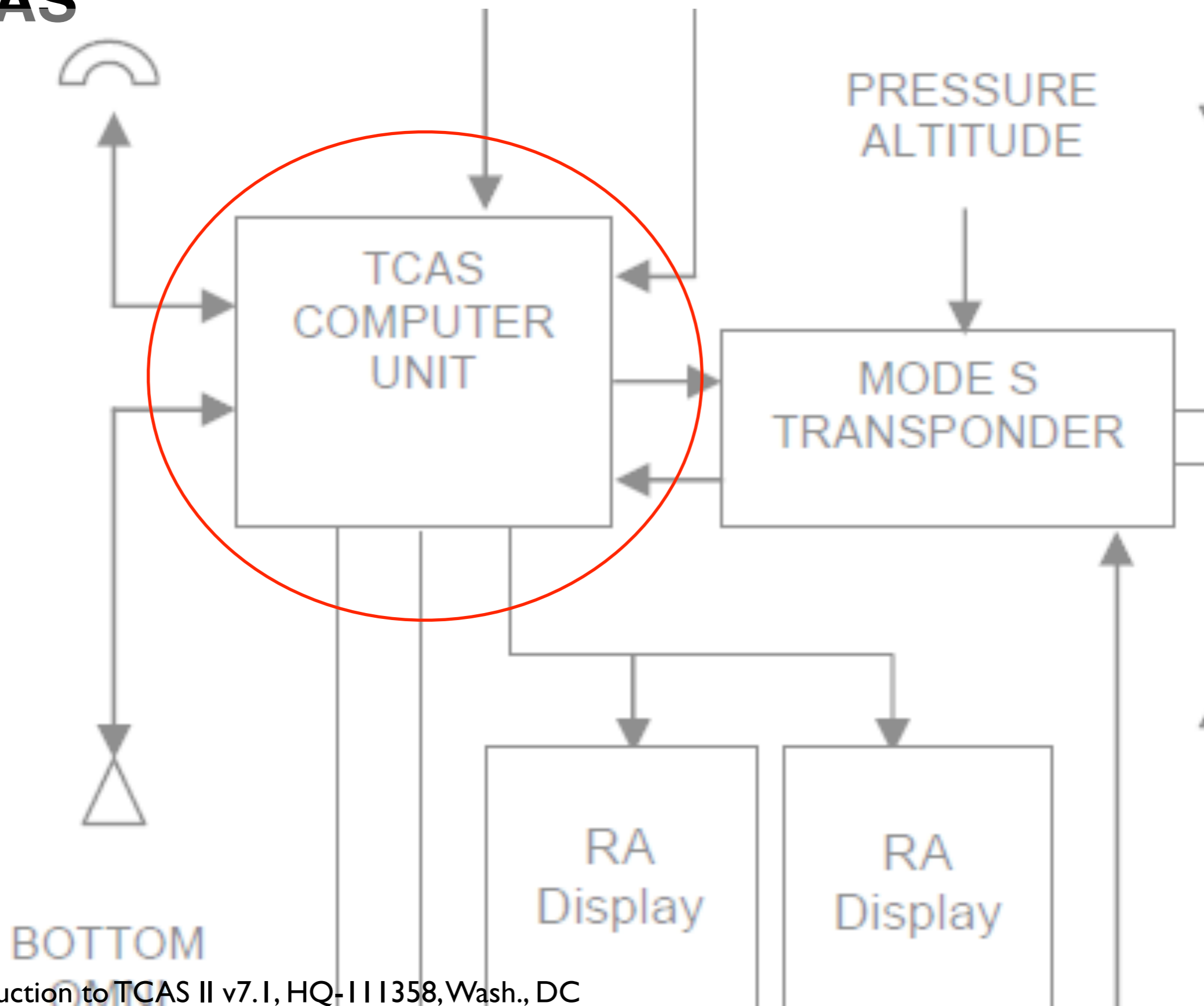


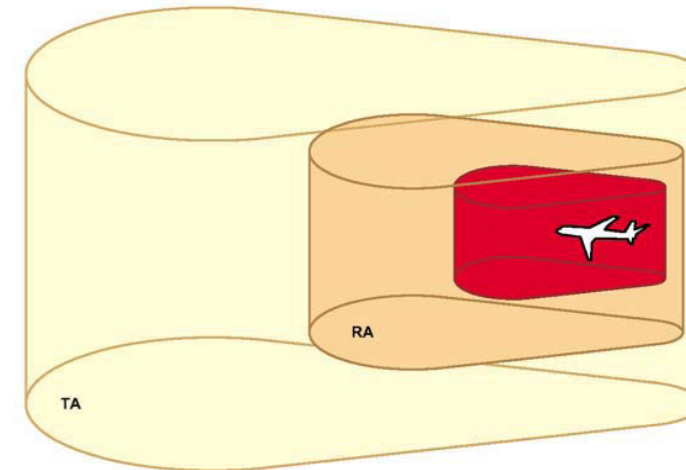
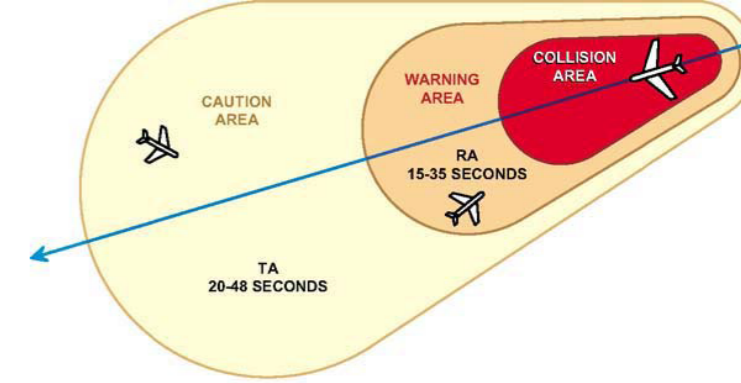
Fig 2. TCAS II Block Diagram

# TCAS

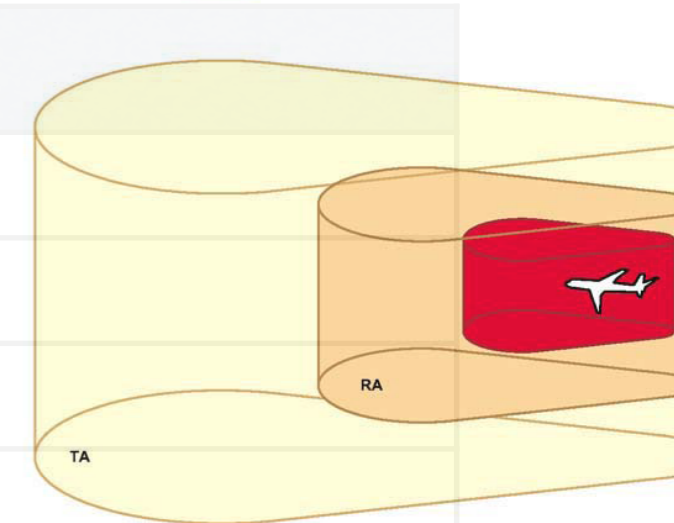
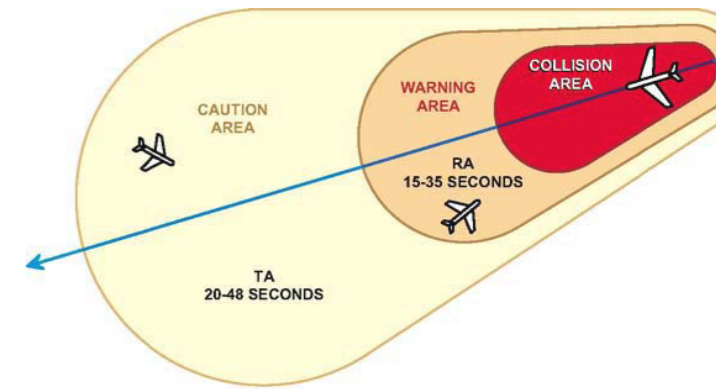


# TCAS inputs

	Input	Type
1	Cur_Vertical_Sep	<i>continuous</i>
2	High_Confidence	<i>boolean</i>
3	Two_of_Three_Reports_Valid	<i>boolean</i>
4	Own_Tracked_Alt	<i>discrete</i>
5	Other_Tracked_Alt	<i>discrete</i>
6	Own_Tracked_Alt_Rate	<i>continuous</i>
7	Alt_Layer_Value	<i>discrete</i>
8	Up_Separation	<i>continuous</i>
9	Down_Separation	<i>continuous</i>
10	Other_RAC	<i>discrete</i>
11	Other_Capability	<i>discrete</i>
12	Climb_Inhibit	<i>boolean</i>

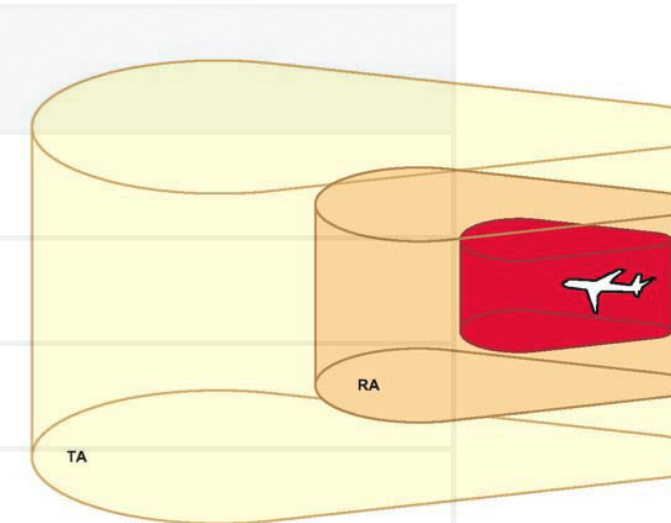
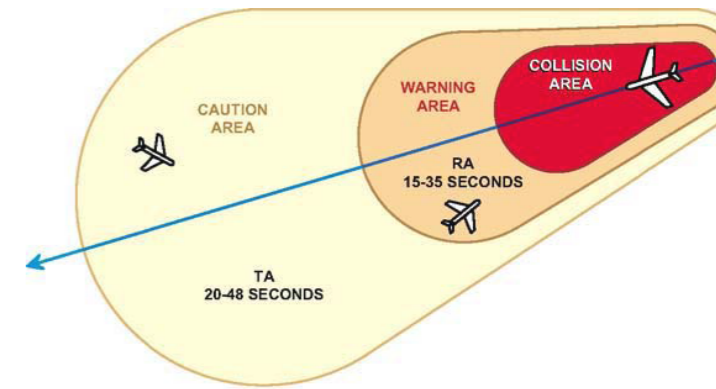


# TCAS - design specification



	Input	Levels
1	Cur_Vertical_Sep	299, 300, 601
2	High_Confidence	boolean
3	Two_of_Three_Reports_Valid	boolean
4	Own_Tracked_Alt	1, 2
5	Other_Tracked_Alt	1, 2
6	Own_Tracked_Alt_Rate	600, 601
7	Alt_Layer_Value	0, 1, 2, 3
8	Up_Separation	0, 399, 400, 499, 500, 639, 640, 739, 740, 840
9	Down_Separation	0, 399, 400, 499, 500, 639, 640, 739, 740, 840
10	Other_RAC	NO_INTENT, DO_NOT_CLIMB, DO_NOT_DESCEND
11	Other_Capability	TCAS_TA, OTHER
12	Climb_Inhibit	boolean

# TCAS - design specification

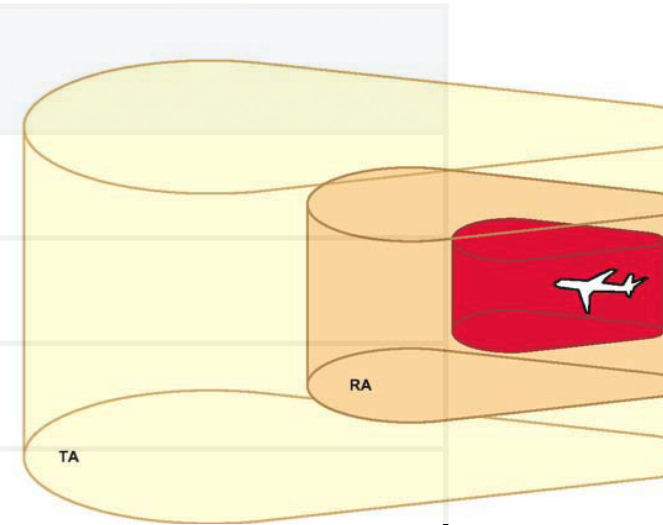
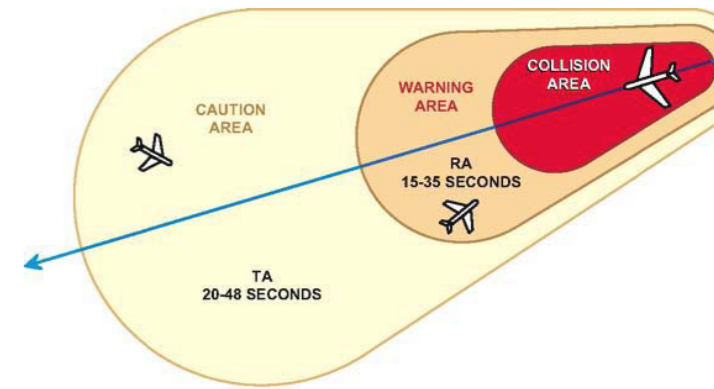


	Input	Levels
1	Cur_Vertical_Sep	299, 300, 601
2	High_Confidence	boolean
3	Two_of_Three_Reports_Valid	boolean
4	Own_Tracked_Alt	1, 2
5	Other_Tracked_Alt	1, 2
6	Own_Tracked_Alt_Rate	600, 601
7	Alt_Layer_Value	0, 1, 2, 3
8	Up_Separation	0, 399, 400, 499, 500, 639, 640, 739, 740, 840
9	Down_Separation	0, 399, 400, 499, 500, 639, 640, 739, 740, 840
10	Other_RAC	NO_INTENT, DO_NOT_CLIMB, DO_NOT_DESCEND
11	Other_Capability	TCAS_TA, OTHER
12	Climb_Inhibit	boolean

**Exhaustive testing is still impossible!**

**Input space:  $3 \cdot 2^5 \cdot 4 \cdot 10^2 \cdot 3 \cdot 2^2 = 460,800$  points**

# TCAS - design specification



	Input	Levels
1	Cur_Vertical_Sep	299, 300, 601
2	High_Confidence	boolean
3	Two_of_Three_Reports_Valid	boolean
4	Own_Tracked_Alt	1, 2
5	Other_Tracked_Alt	1, 2
6	Own_Tracked_Alt_Rate	600, 601
7	Alt_Layer_Value	0, 1, 2, 3
8	Up_Separation	0, 399, 400, 499, 500, 639, 640, 739, 740, 840
9	Down_Separation	0, 399, 400, 499, 500, 639, 640, 739, 740, 840
10	Other_RAC	NO_INTENT, DO_NOT_CLIMB, DO_NOT_DESCEND
11	Other_Capability	TCAS_TA, OTHER
12	Climb_Inhibit	boolean

How about using a **CA**(N, t, (10<sup>2</sup> · 4 · 3<sup>2</sup> · 2<sup>7</sup>))?

# Case Study #2

## XGBoost

# XGBoost

What is XGBoost?

*“An optimized distributed gradient boosting library designed to be highly **efficient, flexible and portable.**<sup>1</sup>”*

<sup>1</sup>T. Chen and C. Guestrin. 2016. XGBoost: A Scalable Tree Boosting System.

# Combinatorial Testing: XGBoost

	Hyperparameter	Type
1	Max_depth	<i>continuous</i>
2	Subsample	<i>continuous</i>
3	Colsample_bytree	<i>continuous</i>
4	Min_child_weight	<i>continuous</i>
5	Alpha	<i>continuous</i>
6	Lambda	<i>continuous</i>
7	Learning_rate	<i>continuous</i>
8	Iterations	<i>continuous</i>
9	Tree_method	<i>categorical (6)</i>
10	Predictor	<i>categorical (2)</i>
11	Grow_policy	<i>categorical (2)</i>
12	Booster	<i>categorical (3)</i>
13	Process_type	<i>categorical (2)</i>
14	Sample_type	<i>categorical (2)</i>
15	Feature_selector	<i>categorical (4)</i>
16	Colsample_bylevel	<i>continuous</i>
17	Colsample_bynode	<i>continuous</i>
18	Max_delta_step	<i>continuous</i>

	Hyperparameter	Type
19	Gamma	<i>continuous</i>
20	Scale_pos_weight	<i>continuous</i>
21	Num_parallel_tree	<i>continuous</i>
22	Base_score	<i>continuous</i>
23	Nthread	<i>continuous</i>
24	Seed	<i>continuous</i>
25	Sketch_eps	<i>continuous</i>
26	Refresh_leaf	<i>continuous</i>
27	Max_leaves	<i>continuous</i>
28	Max_bin	<i>continuous</i>
29	Rate_drop	<i>continuous</i>
30	One_drop	<i>continuous</i>
31	Skip_drop	<i>continuous</i>
32	Top_k	<i>continuous</i>
33	Tweedie_variance_power	<i>continuous</i>
34	Normalize_type	<i>categorical (2)</i>

# Combinatorial Testing: XGBoost

	Hyperparameter	Type
1	Max_depth	<i>continuous</i>
2	Subsample	<i>continuous</i>
3	Colsample_bytree	<i>continuous</i>
4	Min_child_weight	<i>continuous</i>
5	Alpha	<i>continuous</i>
6	Lambda	<i>continuous</i>
7	Learning_rate	<i>continuous</i>
8	Iterations	<i>continuous</i>
9	Tree_method	<i>categorical (6)</i>
10	Predictor	<i>categorical (2)</i>
11	Grow_policy	<i>categorical (2)</i>
12	Booster	<i>categorical (3)</i>
13	Process_type	<i>categorical (2)</i>
14	Sample_type	<i>categorical (2)</i>
15	Feature_selector	<i>categorical (4)</i>
16	Colsample_bylevel	<i>continuous</i>
17	Colsample_bynode	<i>continuous</i>
18	Max_delta_step	<i>continuous</i>

	Hyperparameter	Type
19	Gamma	<i>continuous</i>
20	Scale_pos_weight	<i>continuous</i>
21	Num_parallel_tree	<i>continuous</i>
22	Base_score	<i>continuous</i>
23	Nthread	<i>continuous</i>
24	Seed	<i>continuous</i>
25	Sketch_eps	<i>continuous</i>
26	Refresh_leaf	<i>continuous</i>
27	Max_leaves	<i>continuous</i>
28	Max_bin	<i>continuous</i>
29	Rate_drop	<i>continuous</i>
30	One_drop	<i>continuous</i>
31	Skip_drop	<i>continuous</i>
32	Top_k	<i>continuous</i>
33	Tweedie_variance_power	<i>continuous</i>
34	Normalize_type	<i>categorical (2)</i>

**Challenge:** Derive test cases to validate the hyperparameters.

# Combinatorial Testing: XGBoost

	Input	# of levels
1	Max_depth	3
2	Subsample	3
3	Colsample_bytree	3
4	Min_child_weight	3
5	Alpha	3
6	Lambda	3
7	Learning_rate	3
8	Iterations	3
9	Tree_method	6
10	Predictor	2
11	Grow_policy	2
12	Booster	3
13	Process_type	2
14	Sample_type	2
15	Feature_selector	4
16	Colsample_bylevel	3
17	Colsample_bynode	3
18	Max_delta_step	3

	Input	# of levels
19	Gamma	3
20	Scale_pos_weight	3
21	Num_parallel_tree	3
22	Base_score	3
23	Nthread	3
24	Seed	3
25	Sketch_eps	3
26	Refresh_leaf	2
27	Max_leaves	3
28	Max_bin	3
29	Rate_drop	3
30	One_drop	2
31	Skip_drop	3
32	Top_k	3
33	Tweedie_variance_power	3
34	Normalize_type	2

# Combinatorial Testing: XGBoost

	Input	# of levels
1	Max_depth	3
2	Subsample	3
3	Colsample_bytree	3
4	Min_child_weight	3
5	Alpha	3
6	Lambda	3
7	Learning_rate	3
8	Iterations	3
9	Tree_method	6
10	Predictor	2
11	Grow_policy	2
12	Booster	3
13	Process_type	2
14	Sample_type	2
15	Feature_selector	4
16	Colsample_bylevel	3
17	Colsample_bynode	3
18	Max_delta_step	3

	Input	# of levels
19	Gamma	3
20	Scale_pos_weight	3
21	Num_parallel_tree	3
22	Base_score	3
23	Nthread	3
24	Seed	3
25	Sketch_eps	3
26	Refresh_leaf	2
27	Max_leaves	3
28	Max_bin	3
29	Rate_drop	3
30	One_drop	2
31	Skip_drop	3
32	Top_k	
33	Tweedie_variance_power	
34	Normalize_type	

**Exhaustive testing is impossible!!**

**Input space:  $6 \cdot 4 \cdot 3^{25} \cdot 2^7 = 2,602,870,608,208,896$  points**

**TCAS, XGBoost, the  
Profiler & *more*:  
Combinatorial Testing in Practice**



# Q&A

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**Thank You**

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